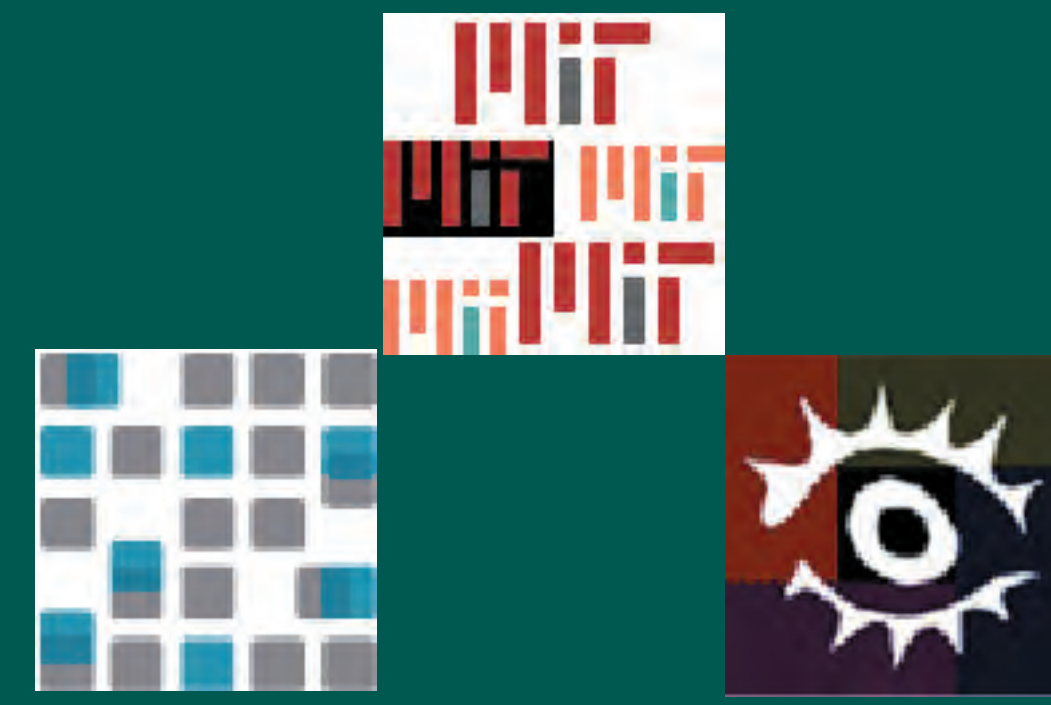


# Seeing the {Closed+Camouflage+Natural=Forest} for the Trees: Rapid Scene Categorization can be mediated by conjunctions of global scene properties

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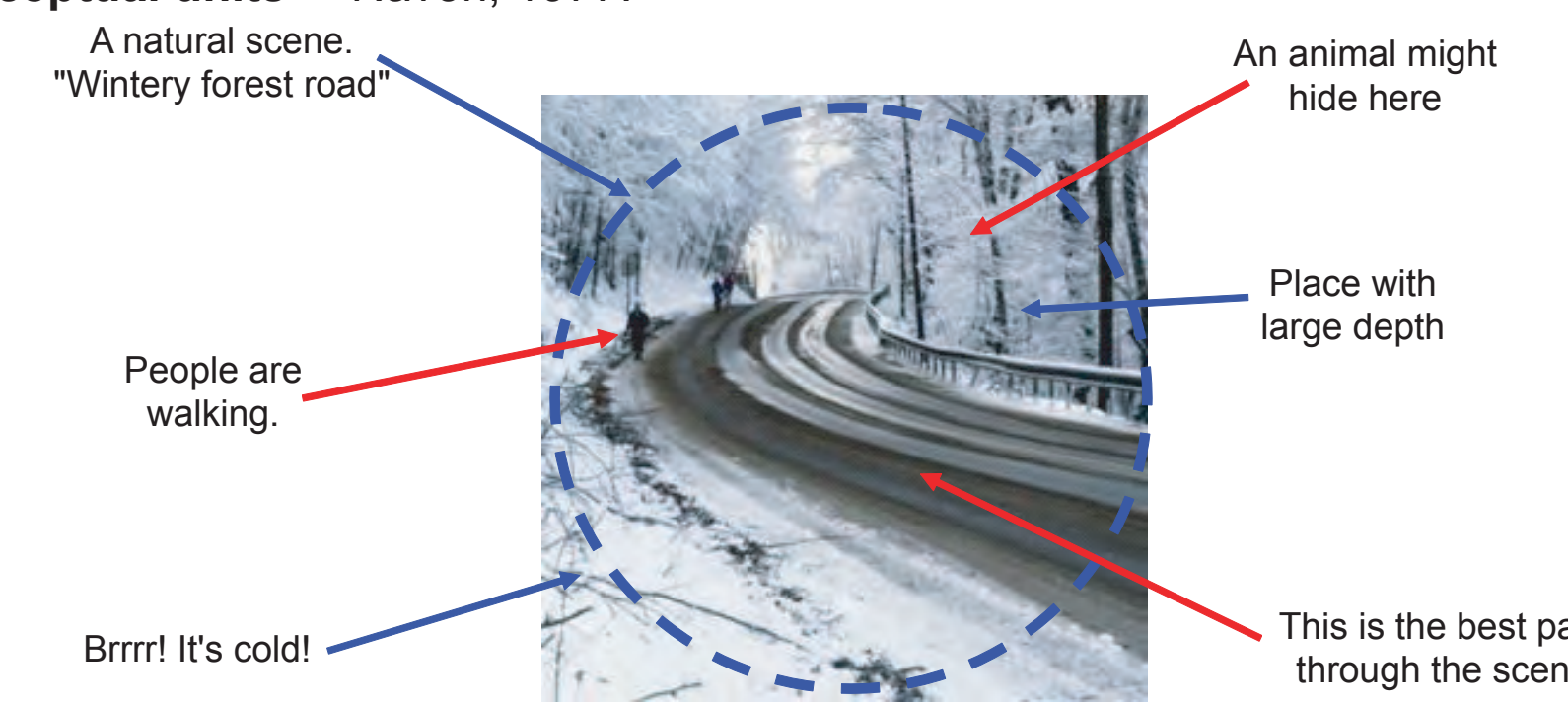
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## Introduction

A A HHHH P Q M M M  
 A A H H H H P Q Q M M M  
 A A A H H H P Q Q M M M  
 A A H H H H P Q Q M M M  
 A A H H H H P P P Q Q Q M M M

"No attempt was made here to formulate an operational definition of globality of visual features which enable precise predictions about the course of perception of real-world stimuli. What is suggested in this paper is that whatever the perceptual units are, the spatial relationships among them is more global than the structure within them.... Thus, I am afraid that operational measures for globality will have to patiently await the time that we have a better idea of how a scene is composed into perceptual units" - Navon, 1977.



- Questions:
1. What is global information in a scene?
  2. How is this information used by human observers?
  3. How does it compare to local (object-centered) information in scenes?

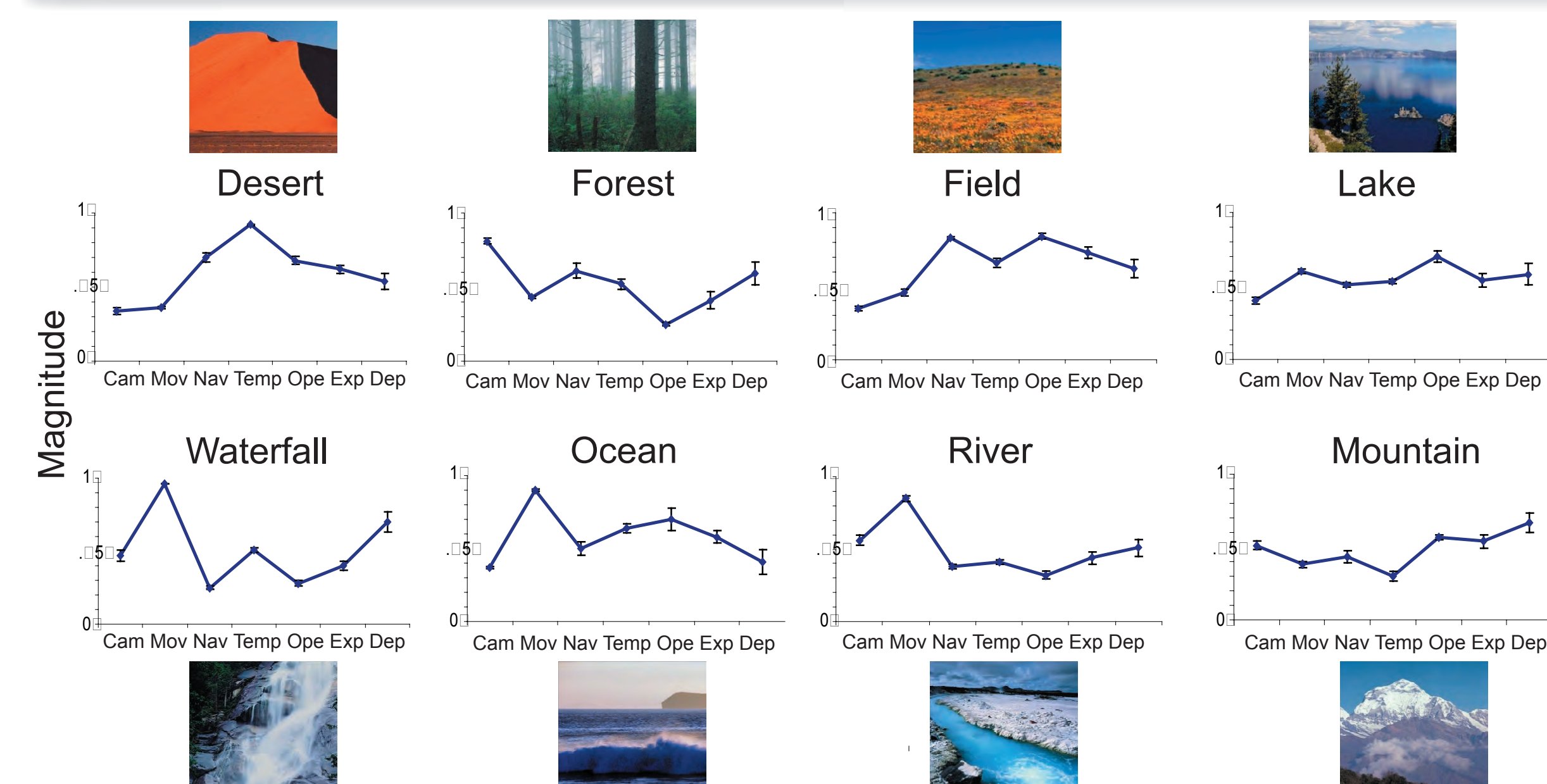
## Global scene properties

A set of properties that describe the **space** that a scene subtends, the possible **interactions** a human can have in the space, or properties of the **surfaces** in the scene.

<b>Space</b>	<b>Interaction</b>	<b>Surface</b>
Degree of openness	Degree of camouflage	Temperature
Mean depth	Navigability	Degree of movement
Degree of expansion		

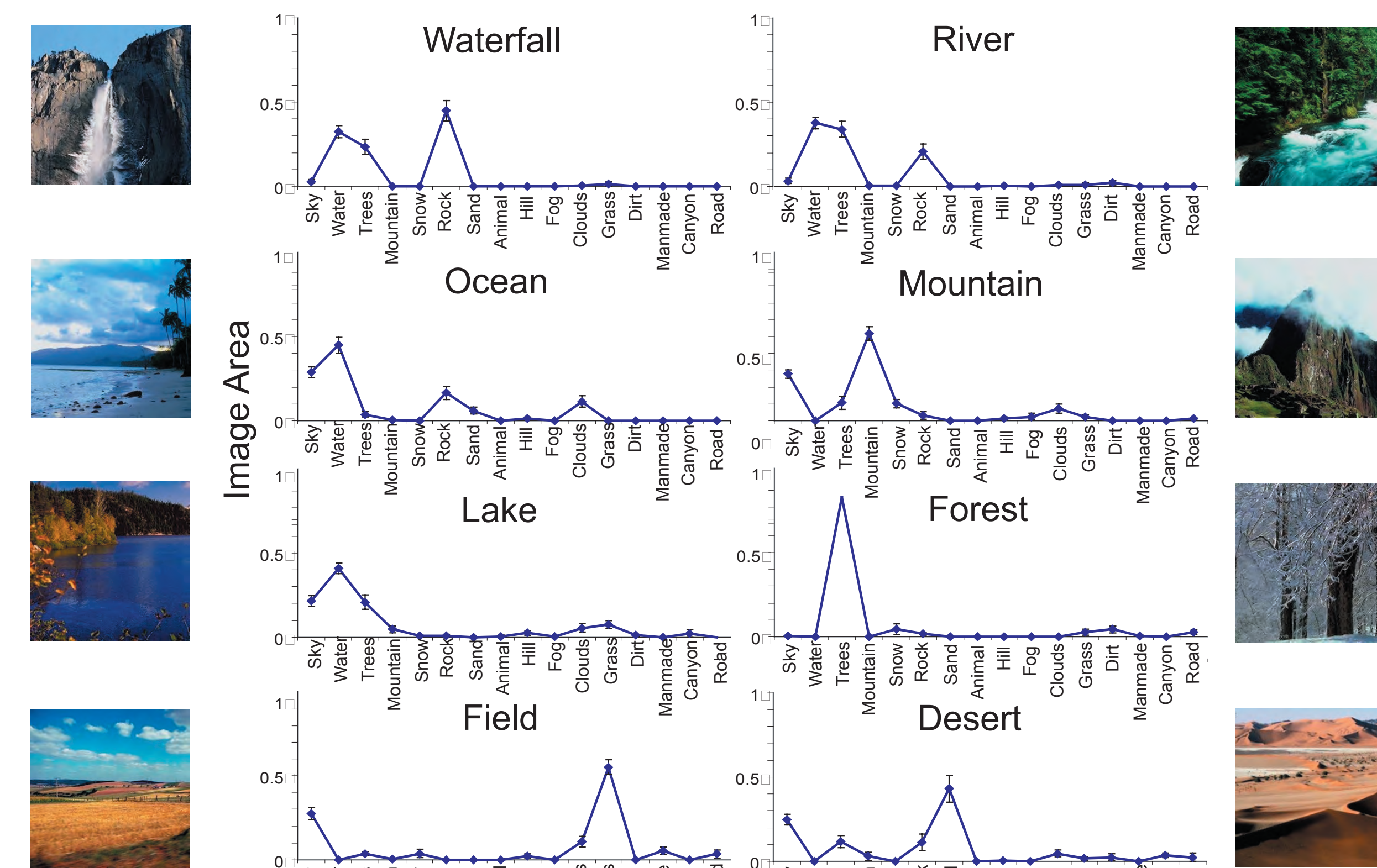
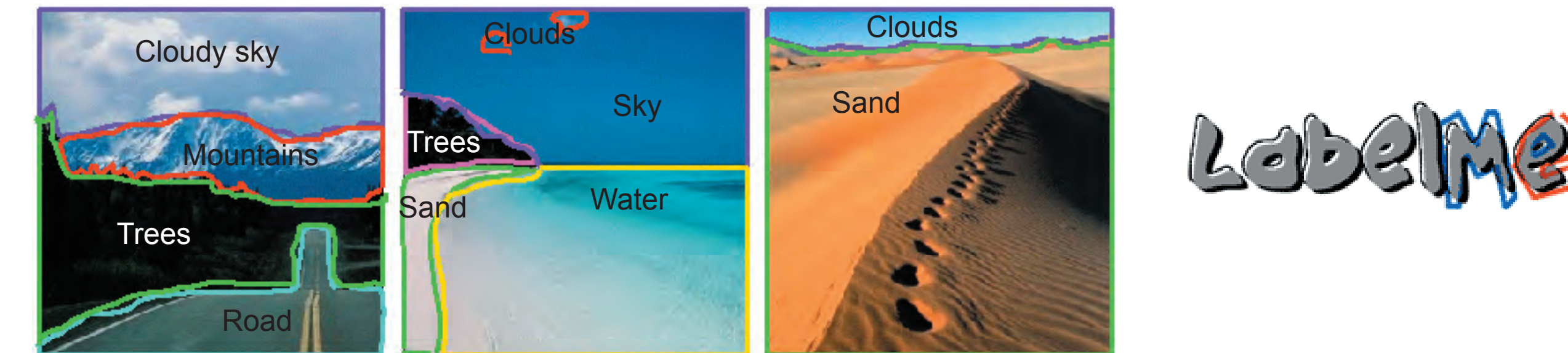
200 images from 8 semantic categories were ranked along these 7 dimensions by 55 observers.

## Ranking Results



## Local object database norming

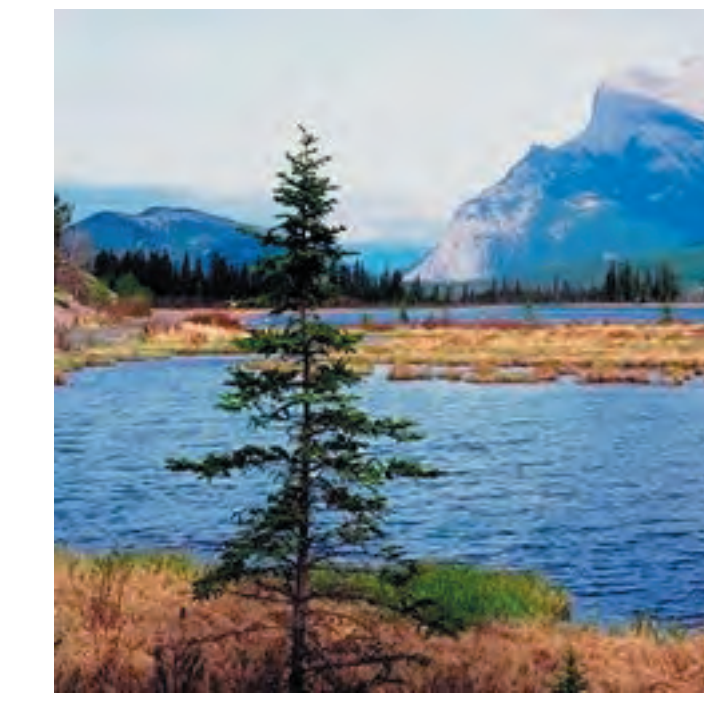
Two observers hand annotated all regions in the 200 image database:



## Sufficiency of global properties

To what extent is global property information or object information alone sufficient to predict human categorization performances?

<b>Global =</b>	<b>Local =</b>
41% camouflage	23% sky
61% moving	35% water
47% navigable	18% trees
32% hot	12% mountain
66% open	1% hill
64% expansive	1% clouds
74% deep	23% grass

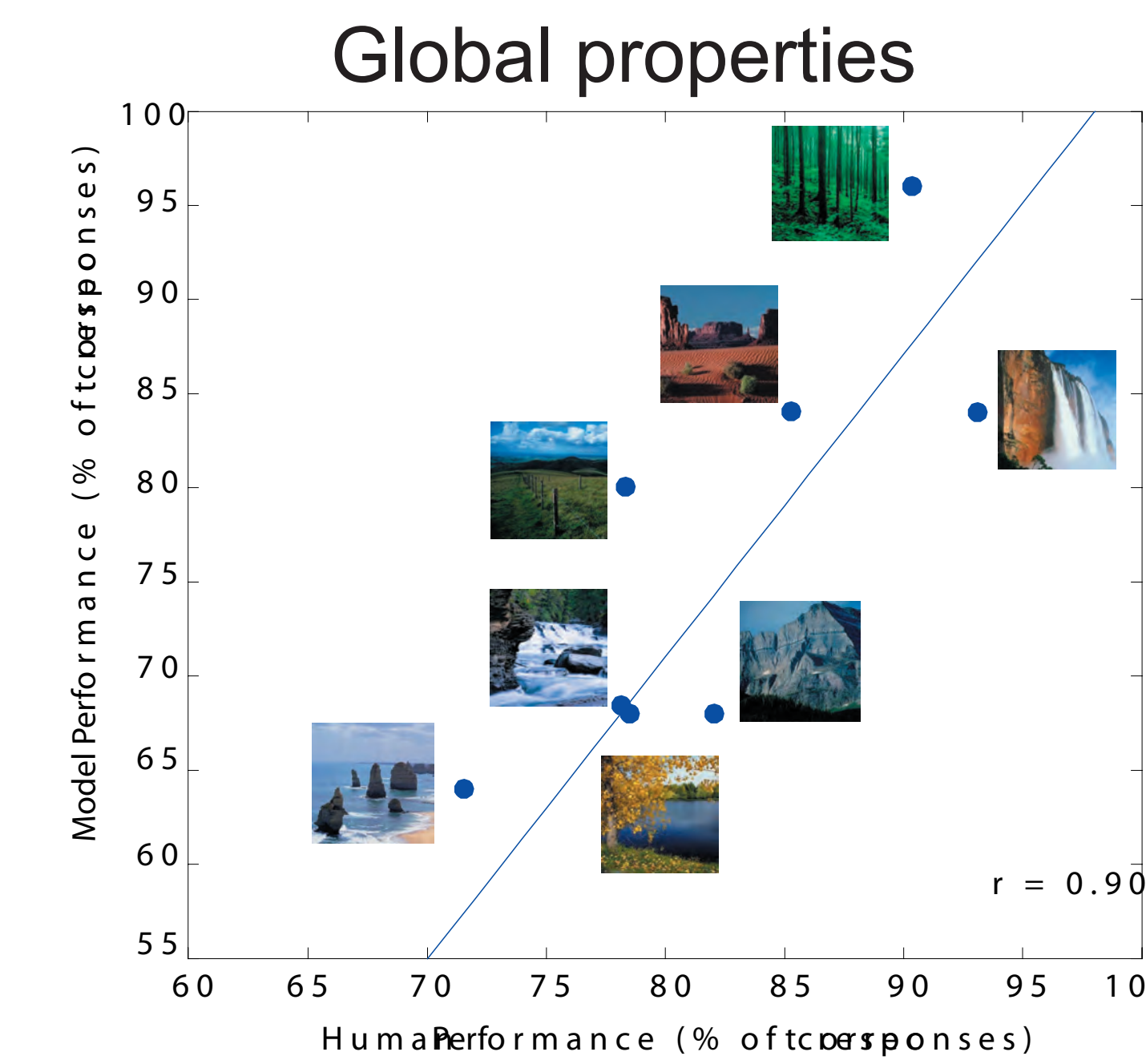


"Lake"

We compared two model observers trained on either the magnitude distributions of global properties across semantic categories or the pixel areas of object concepts across semantic categories.

Assuming Gaussian distributions of representation primitives, the models output the maximum likelihood category for each test image:

$$h_{ML} = \arg \max_{h \in H} \sum_{i=1}^m \ln \frac{1}{\sqrt{2\pi\sigma^2}} - \frac{1}{2\sigma^2} (d_i - h(x_i))^2$$



These 7 global properties alone predict human semantic classification ( $r=0.90$ ,  $p=0.003$ ).

Furthermore, for errors that the model makes, humans make the same errors on 69% of the images.

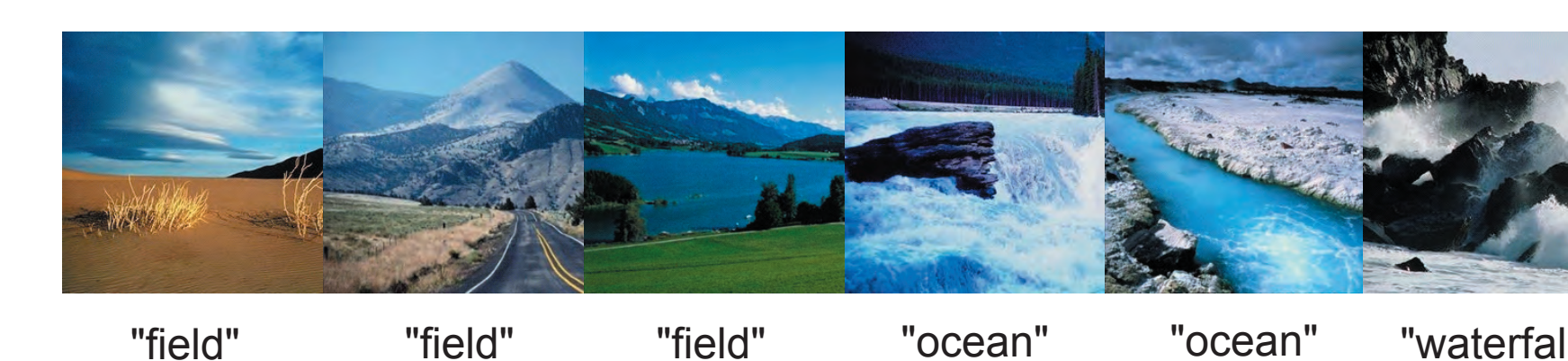
The model using an object representation does not predict as well human semantic classification performance ( $r=0.67$ ,  $p=0.06$ ) by category. It also predicts fewer of the specific errors that humans make (62%).

## Error analysis

Humans and model OK:

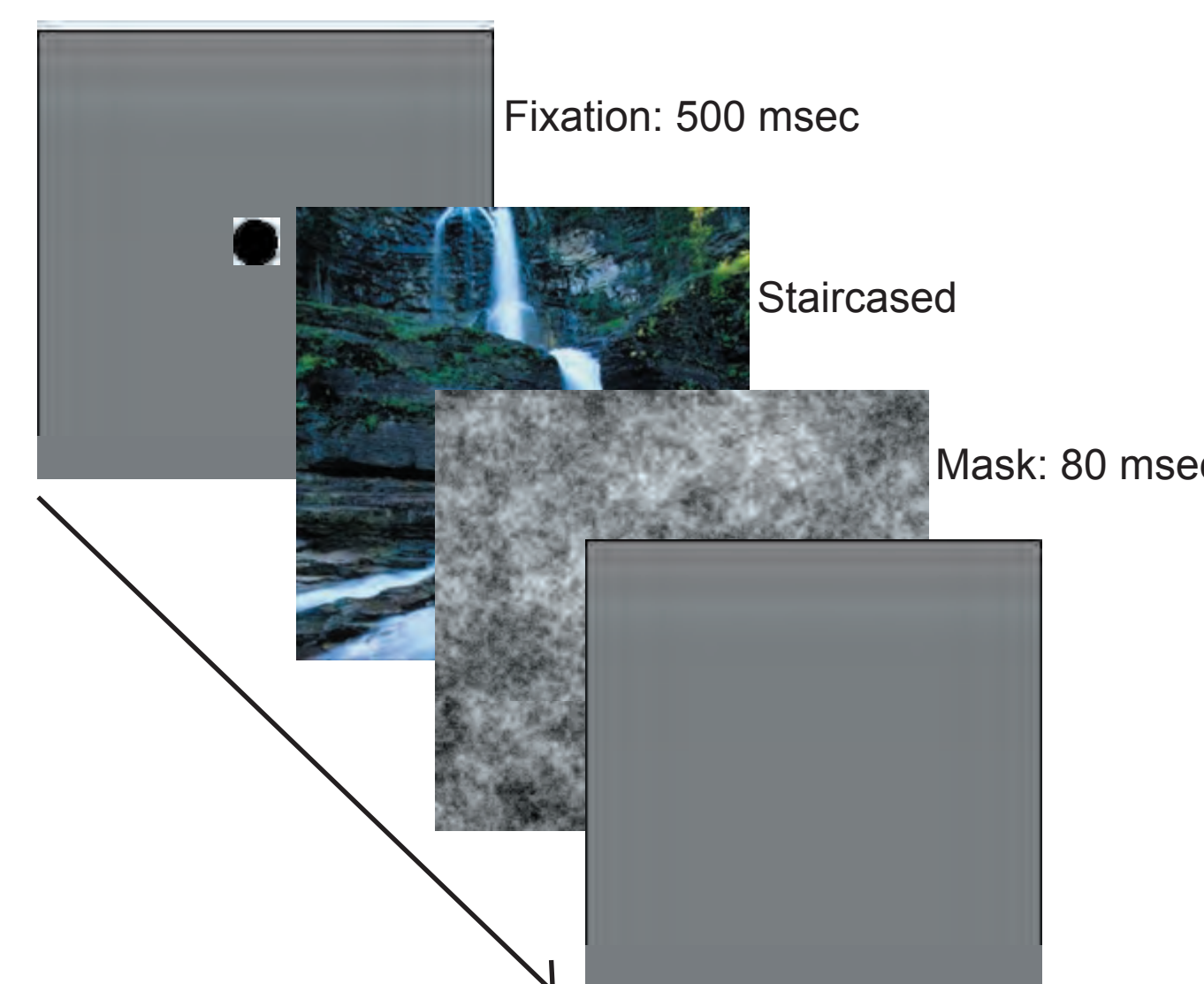


Humans and model miss:



## Perceptual availability of global properties

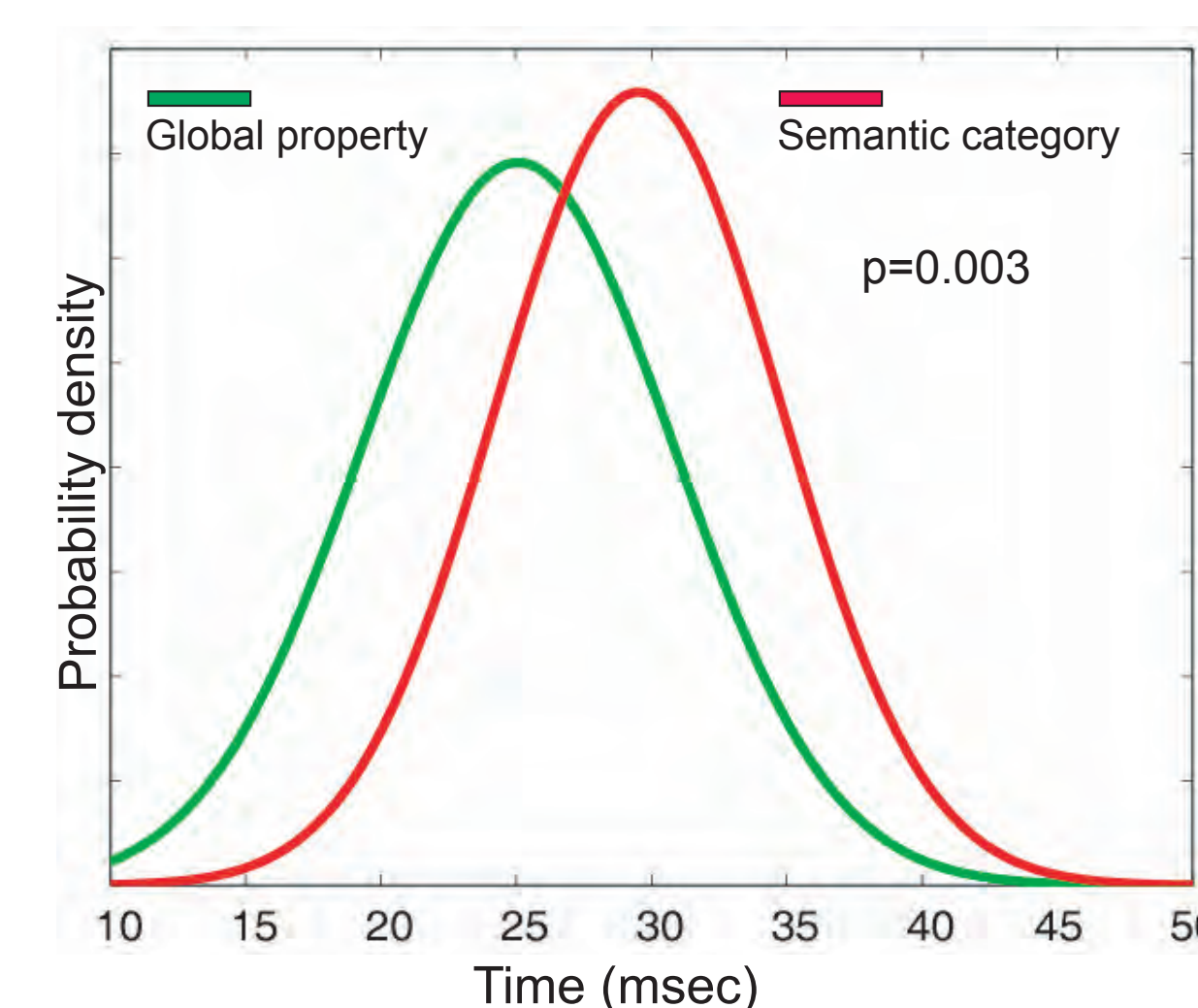
What is the perceptual availability of global properties relative to semantic categories?



We compared GLOBAL property classification to SEMANTIC category classification in a staircased yes-no forced choice task.

Threshold is presentation time permitting 75% correct classifications.

Global properties	Semantic categories
Temperature	15.4
Desert	19.8
Navigation	20.6
Camouflage	21.3
Forest	21.7
Expansion	22.8
Depth	23.0
Waterfall	26.7
Movement	28.5
Openness	29.9
Lake	32.3
Mountain	32.5
River	34.2
Field	34.3



Humans OK, model misses:



Model OK, humans miss:

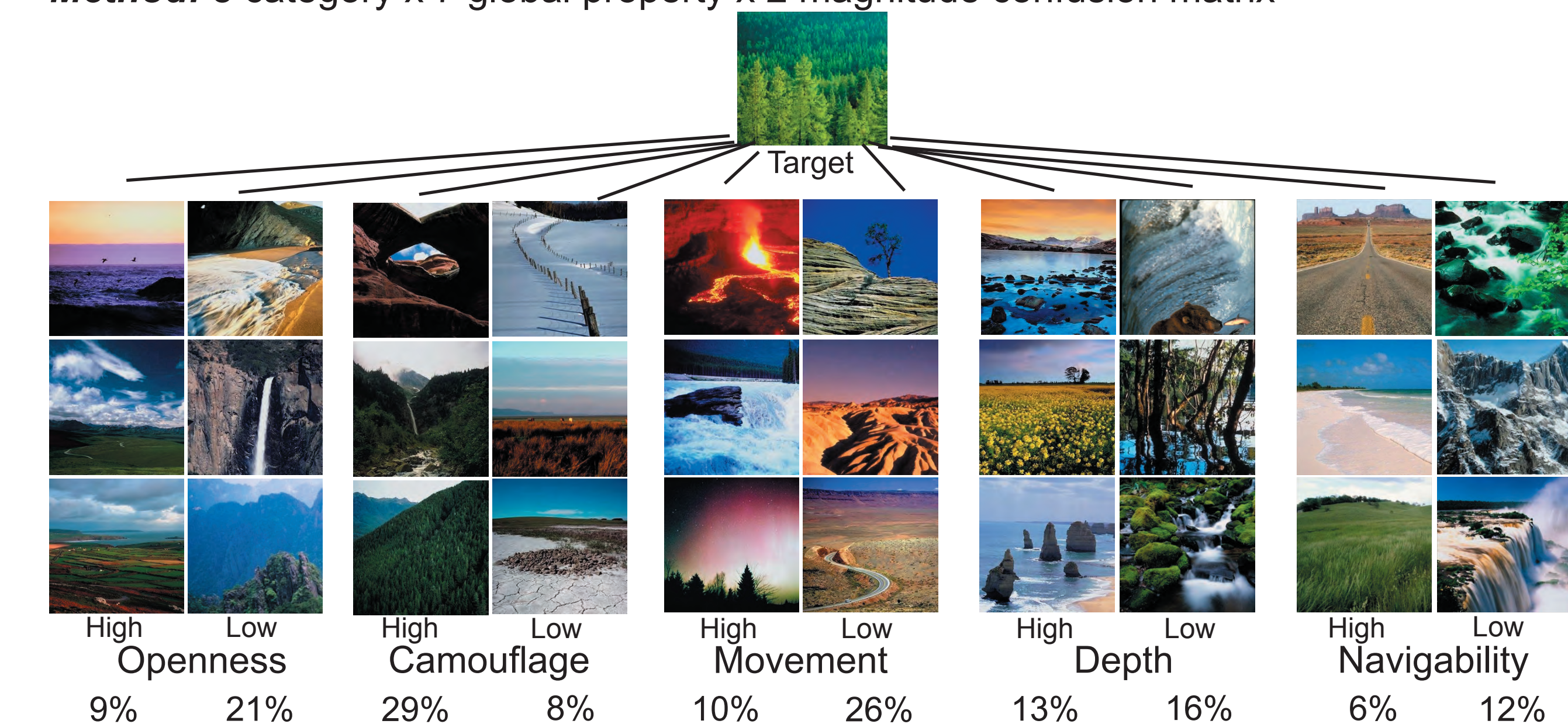


## Use of global properties

These global properties are sufficient to predict human rapid image classification, but are they employed by human observers when doing the task?

**Hypothesis:** If global property information is used by people in rapid semantic classification, then responding to a target among distractors that share the target category's global properties should yield more false alarms than distractor sets that do not share global properties with the target category.

**Method:** 8 category x 7 global property x 2 magnitude confusion matrix



## False alarm rates

Recall that forests were ranked to be closed, high-camouflage, non-moving places.

For all categories across all global properties, there is a significant correlation between the magnitude of the global property ranking and the false alarm rate ( $r=0.47$ ,  $p<0.01$ ).

## Discussion

Global properties are holistic properties related to the shape of scene space, interactions humans can have in that space or properties of the surfaces in the scene.

Global properties have an earlier perceptual availability than the semantic category of images.

Global properties are sufficient to predict human semantic categorization performance and the specific errors made.

It seems that people use global properties to do rapid image classification.

## Thanks

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